


FEM

- For a 2D body, the stresses, strains with initial strain are related as $\rightarrow \sigma = D(\epsilon - \epsilon_0)$
- From the theory of mechanics of solids, for plane stress conditions the initial strain, ϵ_0 can be written as \rightarrow
- What is the size of the element body force vector, f^e of a 2D element? $\rightarrow 6 \times 1$
- Which of the following represents the 2D element Stiffness matrix K^e $\rightarrow t_c A_e B^T D B$
- In a 2D element, what is the size of the element strain displacement matrix? $\rightarrow 3 \times 6$
- From the knowledge of area of triangle, what is the value of $\det J$ in terms of area of the triangle? \rightarrow twice the area of the triangle
- For a 2D element, what is $\det J$ when J is denoted as the Jacobian of the transformation? \rightarrow
- What is the Jacobian matrix size of a basic linear 2D element? $\rightarrow 2 \times 2$
- In a 2D element, $N_2 = 0.25$, $N_3 = 0.3$ what is the value of N_1 ? $\rightarrow 0.45$
- In a 2D element, $N_1 = 0.3$, $N_2 = 0.2$ what is the value of N_3 ? $\rightarrow 0.5$
- What is the size of the shape function matrix N , of a 2D element? $\rightarrow 2 \times 6$
- In a 2D element, the shape functions can be physically represented by area coordinates. A point in a triangle divides it into three areas, . The shape N_1 is represented as $\rightarrow A_1/A$
- In a 2D element, what is the value of summation of all the shape functions at every point inside the triangle? $\rightarrow 1$
- In a 2D element, the value of shape function N_2 at node 1 is \rightarrow zero
- In a 2D element, the value of shape function N_1 at node 1 is $\rightarrow 1$
- The number of shape functions in a 2D element is $\rightarrow 3$
- In a 2D problem, for the constant strain triangle, the shape functions varies over the element as \rightarrow Linear
- The element displacement vector for a 2D element is $\rightarrow q = [q_1, q_2, q_3, q_4, q_5, q_6]^T$
- The number of nodes present in a basic 2D linear element is $\rightarrow 3$
- In a 2D problem, what is the degree of freedom of each node? $\rightarrow 2$
- In a 2D problem, the basic 2D element is \rightarrow triangle
- In a 2D problem, the stress-strain relationship is represented as $\rightarrow \sigma = D \epsilon$
- In a 2D problem, the shear strain in XY direction is given as $\rightarrow (du/dy + dv/dx)$
- In a 2D body, the elemental volume (dv) is given as $\rightarrow t dA$
- In a 2D problem, the strain and its components are given as $\rightarrow \epsilon =$
- In a 2D problem, the stress and its components are given as $\rightarrow \sigma =$
- In a 2D problem, the displacement vector is given as $\rightarrow u = [u, v]^T$
- What is the size of the element stiffness matrix K_e of a beam element? $\rightarrow 4 \times 4$
- The total number of shape functions in a hermite shape function are $\rightarrow 4$
- In a beam element, the hermite shape function is represented by an expression of order \rightarrow cubic order
- In a beam element, the element displacement vector is $\rightarrow q = [q_1, q_2, q_3, q_4]^T$
- In a beam element, what is the degree of freedom of each node? $\rightarrow 2$
- As per the elementary beam theory, the relationship between σ , M and I is $\rightarrow \sigma \times I = -M y$
- What do you mean by a Beam \rightarrow Slender member used for supporting transverse loading
- In a quadratic element, what is the size of element body force vector, f_e $\rightarrow 3 \times 1$
- In a quadratic element, what is the size of element Traction force vector, T_e $\rightarrow 3 \times 1$
- In a quadratic element, what is the size of element stiffness matrix, K $\rightarrow 3 \times 3$
- In a quadratic element, what is the size of element displacement vector, q $\rightarrow 3 \times 1$
- In a quadratic element, what is the size of shape function matrix, N $\rightarrow 1 \times 3$
- In a quadratic element, the quadratic shape function N_3 is denoted as $\rightarrow (1+\xi)(1-\xi)$
- In a quadratic element, the quadratic shape function N_2 is denoted as \rightarrow

42. In a quadratic element, the quadratic shape function 'N1' is denoted as $\rightarrow \xi(1-\xi)$
43. In a quadratic element, what is the value of ξ at node 3 $\rightarrow 0$
44. In a quadratic element, what is the value of ξ at node 2 $\rightarrow 1$
45. In a quadratic element, what is the value of ξ at node 1 $\rightarrow -1$
46. In a quadratic element, what is the element displacement vector 'q' $\rightarrow q=[q_1, q_2, q_3]^T$
47. In a quadratic element what is the internal node $\rightarrow 3$
48. What is the value of deformation at fixed end of a cantilever beam when it is subjected to point load at free end. \rightarrow ZERO
49. For linear one dimensional problem, what is the size of the global stiffness matrix when 'N' denotes the number nodes? $\rightarrow N \times N$
50. In a 1D problem, what is the value of integral of a shape function $\rightarrow 1$
51. In a 1D problem, the element traction force vector, T_e , is given as \rightarrow 
52. In a 1D problem, the element body force vector, f_e , is denoted as \rightarrow 
53. In a 1D problem, what is the size of the element stiffness matrix, K $\rightarrow 2 \times 2$
54. In a 1D problem, what is the relationship between ϵ , B and q . $\rightarrow \epsilon = Bq$
55. In a 1D problem, what is the size of the element strain-displacement matrix, B is $\rightarrow 1 \times 2$
56. In a 1D problem, the isoparametric formulation in terms of N_1 and N_2 as $\rightarrow x = \frac{1}{2}(x_1 + x_2) + \frac{1}{2}(x_2 - x_1)\xi$
57. In a 1D problem, the element displacement vector q is denoted as $\rightarrow q = [q_1, q_2]^T$
58. In a 1D problem, the shape function matrix 'N' is denoted as $\rightarrow N = \left[\frac{1-\xi}{2}, \frac{1+\xi}{2} \right]$
59. In a 1D problem, the linear displacement field within the element can be written in terms of the nodal displacements q_1 and q_2 in matrix notation as $\rightarrow u = Nq$
60. In a 1D problem, the linear displacement field within the element can be written in terms of the nodal displacements q_1 and q_2 as $\rightarrow \frac{1}{2}(q_1 + q_2) + \frac{1}{2}(q_2 - q_1)\xi$
61. In a 1D problem, the linear shape function N_1 is denoted as $\rightarrow (1-\xi)/2$
62. In a 1D problem, the linear shape function N_2 is denoted as $\rightarrow (1+\xi)/2$
63. In a 1D problem, the length of an element is covered when natural coordinate, ξ changes from $\rightarrow -1$ to 1
64. What do you mean by element connectivity in a finite element modeling? \rightarrow It establishes local-global correspondence
65. In a 1D problem stepped bar with 4 steps is discretized into 4 linear elements then what are the number of nodes present in the problem $\rightarrow 5$
66. In a 1D problem, stepped bar with 3 steps is discretized into 3 linear elements then what are the number of nodes present in the problem $\rightarrow 4$
67. In a 1D problem, stepped bar with 2 steps is discretized into 2 linear elements then what are the number of nodes present in the problem $\rightarrow 3$
68. In a 1D problem, what is the degree of freedom (dof) of each node $\rightarrow 1$
69. For 1D problems, the differential volume dv can be written as $\rightarrow A dx$
70. What is the nature of stress-strain curve of a cast iron material? \rightarrow a straight line
71. For linear elastic materials, the strain energy per unit volume in the body is $\rightarrow \frac{1}{2} \epsilon^T \sigma$
72. Under plane strain condition the strain by its components is represented as $\rightarrow \epsilon = \left[\epsilon_x, \epsilon_y, \epsilon_{xy} \right]^T$
73. Under plane stress condition the stress by its components is represented as $\rightarrow \sigma = \left[\sigma_x, \sigma_y, \tau_{xy} \right]^T$
74. The surface traction acting on a 3D body is represented by its components as $\rightarrow T = [T_x, T_y, T_z]^T$
75. Distributed force acting on a 3D body is represented as $\rightarrow f = [f_x, f_y, f_z]^T$
76. A load 'P' acting at a point 'i' is represented by its three components as $\rightarrow P_i = [P_{x_i}, P_{y_i}, P_{z_i}]^T$
77. What is the size of material matrix of a 2D body? $\rightarrow 3 \times 3$
78. What is the size of material matrix of a 3D body? $\rightarrow 6 \times 6$
79. What is the engineering shear strain of a 3D body in YZ direction? $\rightarrow dv/dz + dw/dy$
80. What is the engineering shear strain of a 3D body in XZ direction? $\rightarrow du/dz + dw/dx$
81. What is the engineering shear strain of a 3D body in XY direction? $\rightarrow du/dy + dv/dx$
82. How 2D problems are modeled \rightarrow Modeled as plane stress and plane strain
83. What is a shear strain? \rightarrow Ratio of shear stress and shear modulus
84. What are the units for the coefficient of linear expansion? \rightarrow per deg C
85. Which one of the following refers to the isotropic materials? \rightarrow Material properties are constant in all directions
86. How do you define a stress? \rightarrow Force per unit area
87. What is the traction force of a 1D body? \rightarrow force per unit length
88. What is the traction force of a 2D body? \rightarrow Force per unit area
89. What is the Body Force? \rightarrow force per unit volume
90. In a plane strain condition \rightarrow Strains in Z-direction are zero

92. What is the Poisson's ratio? \rightarrow The ratio of lateral strain to longitudinal strain
93. What is the potential energy of an elastic body? \rightarrow Strain energy + work potential
94. When do you say that a problem is plane-strain problem? \rightarrow If a long body of uniform cross section is subjected to transverse loading along its length.
95. When do you say that a problem is plane-stress problem? \rightarrow If a thin planar body subjected to in-plane loading on its edge surface.
96. In a 1D body what is the relationship between stress and strain \rightarrow
97. In a 2D body what is the relationship between stress and strain \rightarrow
98. In a 3D body what is the relationship between stress and strain \rightarrow
99. What is the relationship between modulus of rigidity and modulus of elasticity in terms of Poisson's ratio? $\rightarrow E = 2G(1+\nu)$
100. In a 3D body what is the strain-displacement relationship in Z-direction? $\rightarrow dw/dz$
101. In a 3D body what is the strain-displacement relationship in Y-direction? $\rightarrow dw/dy$
102. In a 3D body what is the strain-displacement relationship in X-direction? $\rightarrow du/dx$
103. What are the three shear stresses in a 3D element? \rightarrow
104. In a 3D body what are the three normal stresses along the coordinate axis? \rightarrow