

| S.No | QUESTION | Blooms Taxonomy Level | Course Outcome |
|---------------------|--|-----------------------|----------------|
| UNIT-I | | | |
| INTRODUCTION | | | |
| 1 | Define symmetric and anti symmetric signals. | Remember | 1 |
| 2 | Explain about impulse response? | Understand | 2 |
| 3 | Describe an LTI system? | Understand | 1 |
| 4 | List the basic steps involved in convolution? | Remember | 2 |
| 5 | Discuss the condition for causality and stability? | Understand | 1 |
| 6 | State the Sampling Theorem | Remember | 1 |
| 7 | Express and sketch the graphical representations of a unit impulse, step | Understand | 1 |
| 8 | Model the Applications of DSP? | Apply | 2 |
| 9 | Develop the relationship between system function and the frequencyResponse | Apply | 1 |
| 10 | Discuss the advantages of DSP? | Understand | 1 |
| 11 | Explain about energy and power signals? | Understand | 1 |
| 12 | State the condition for BIBO stable? | Remember | 2 |
| 13 | Define Time invariant system. | Remember | 2 |
| 14 | Define the Parseval's Theorem | Remember | 2 |
| 15 | List out the operations performed on the signals. | Remember | 1 |
| 16 | Discuss about memory and memory less system? | Understand | 2 |
| 17 | Define commutative and associative law of convolutions. | Remember | 1 |
| 18 | Sketch the discrete time signal $x(n) = 4\delta(n+4) + \delta(n) + 2\delta(n-1) + \delta(n-2)$ | Apply | 2 |

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| 19 | Identify the energy and power of $x(n) = Ae^{j\omega n} u(n)$. | Apply | 1 |
| 20 | Illustrate the aliasing effect? How can it be avoided? | Apply | 1 |
| 21 | Identify linear system in the following: a) $y(n) = e^{x(n)}$ b) $y(n) = x^2(n)$ c) $y(n) = ax(n) + b$ d) $y(n) = x(n^2)$ | Understand | 1 |
| 22 | Identify a time-variant system. a) $y(n) = e^{x(n)}$ b) $y(n) = x(n^2)$ c) $y(n) = x(n) - x(n-1)$ d) $y(n) = nx(n)$ | Apply | 2 |
| 23 | Identify a causal system. a) $y(n) = x(2n)$ b) $y(n) = x(n) - x(n-1)$ c) $y(n) = nx(n)$ d) $y(n) = x(n) + x(n+1)$ | Evaluate | 1 |
| REALIZATION OF DIGITAL FILTERS | | | |
| 24 | Define Z-transform and region of converges. | Understand | 2 |
| 25 | What are the properties of ROC | Remember | 2 |
| 26 | Write properties of Z-transform | Understand | 2 |
| 27 | Find z-transform of a impulse and step signals | Remember | 2 |
| 28 | What are the different methods of evaluating inverse Z-transform | Evaluate | 2 |
| 29 | Define system function | Understand | 2 |
| 30 | Find The Z-transform of the finite-duration signal $x(n) = \{1, 2, 5, 7, 0, 1\}$ | Understand | 2 |
| 31 | What is the difference between bilateral and unilateral Z-transform | Evaluate | 2 |
| 32 | What is the Z-transform of the signal $x(n) = \cos(\omega_0 n) u(n)$. | Evaluate | 2 |
| 33 | With reference to Z-transform, state the initial and final value theorems? | Analyze | 2 |
| 34 | What are the basic building blocks of realization structures? | Understand | 4 |
| 35 | Define canonic and non-canonic structures. | Remember | 4 |
| 36 | Draw the direct-form I realization of 3 rd order system | Understand | 4 |
| 37 | What is the main advantage of direct-form II realization when compared to Direct-form I realization? | Remember | 4 |
| 38 | What is advantage of cascade realization | Evaluate | 4 |
| 39 | Draw the parallel form structure of IIR filter | Understand | 4 |
| 40 | Draw the cascade form structure of IIR filter | Understand | 4 |
| 41 | Transfer function for IIR Filters | Understand | 4 |
| 42 | Transfer function for FIR Filters | Remember | 4 |

UNIT-I (LONG ANSWER QUESTIONS)

| S. No | QUESTION | Blooms Taxonomy Level | Course Outcome |
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| UNIT-I INTRODUCTION | | | |
| 1 | Determine the impulse response and step response of the causal system given below and discuss on stability: $y(n) + y(n-1) - 2y(n-2) = x(n-1) + 2x(n-2)$ | Evaluate | 1 |

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| 2 | Test the following systems for linearity, time invariance, causality and stability. <ul style="list-style-type: none"> i. $y(n) = a^{ x(n) }$ ii. $y(n) = \sin(2\pi n/F) x(n)$ | Evaluate | 2 |
| 3 | A causal LTI system is defined by the difference equation $2y(n) - y(n-2) = x(n-1) + 3x(n-2) + 2x(n-3)$. Find the frequency response $H(e^{j\omega})$, magnitude response and phase response. | Apply | 2 |
| 4 | Find the impulse response for the causal system $y(n) - y(n-1) = x(n) + x(n-1)$ | Apply | 2 |
| 5 | Define stable and unstable system test the condition for stability of the first-order system governed by the equation $y(n) = x(n) + bx(n-1)$. | Evaluate | 1 |
| 6 | A system is described by the difference equation $y(n) - y(n-1) - y(n-2) = x(n-1)$. Assuming that the system is initially relaxed, determine its unit sample response $h(n)$. | Apply | 2 |
| 7 | A discrete time LTI system has impulse response given by $h(n) = \{1, 3, 2, -1, 1\}$ for $-1 \leq n \leq 3$. Using linearity and time invariance property, determine the system output $y(n)$ if the input $x(n)$ is given by $x(n) = 2\delta(n) - \delta(n-1)$. | Evaluate | 1 |
| 8 | Determine whether the following system is <ul style="list-style-type: none"> i. Linear ii. Causal iii. Stable iv. Time invariant $y(n) = \log_{10} x(n) $ Justify your answer. | Evaluate | 2 |
| 9 | Determine the impulse response and the unit step response of the systems described by the difference equation $y(n) = 0.6y(n-1) - 0.08y(n-2) + x(n)$. | Apply | 2 |
| 10 | The impulse response of LTI system is $h(n) = \{1, 2, 1, -1\}$. Determine the response of the system if input is $x(n) = \{1, 2, 3, 1\}$ | Evaluate | 1 |
| 11 | Determine the output $y(n)$ of LTI system with impulse response $h(n) = a^n u(n)$, $ a < 1$. When the input is unit input sequence that is $x(n) = u(n)$ | Remember | 1 |
| 12 | Determine impulse response for cascade of two LTI systems having impulse responses of $H_1(n) = (1/2)^n u(n)$ and $H_2(n) = (1/4)^n u(n)$ | Apply | 1 |
| 13 | For each impulse response listed below determine whether the corresponding system is (i) causal (ii) stable <ul style="list-style-type: none"> a) $h(n) = 2^n u(-n)$ b) $\sin \frac{n\pi}{2}$ c) $h(n) = \delta(n) + \sin n\pi$ d) $h(n) = e^{2n} u(n-1)$ | Understand | 1 |

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| 14 | Find the Discrete convolution for the following sequence $u(n)*u(n-3)$ | Apply | 1 |
| 15 | Calculate the frequency response for the LTI systems representation i) $H_1(n)=(1/2)^n u(n)$ ii) $h(n)=\delta(n)-\delta(n-1)$ | Remember | 1 |
| 16 | Determine the stability of the system $Y(n)-(5/2)y(n-1)+y(n-2)=x(n)-x(n-1)$ | Evaluate | 2 |
| 17. | Find the response of the following difference equation $y(n)-5y(n-1)+6y(n-2)=x(n)$ for $x(n)=n$ | Apply | 2 |
| REALIZATION OF DIGITAL FILTERS | | | |
| 18. | A causal LTI system is described by the difference equation $y(n)=y(n-1)+y(n-2)+x(n-1)$, where $x(n)$ is the input and $y(n)$ is the output. Find i. The system function $H(Z)=Y(Z)/X(Z)$ for the system, plot the poles and zeroes of $H(Z)$ and indicate the region of convergence. ii. The unit sample response of the system. iii. Is this system stable or not? | Understand | 2 |
| 19. | Find the input $x(n)$ of the system if the impulse response $h(n)$ and output $y(n)$ are shown below $h(n)=\{1\ 2\ 3\ 2\}$ $y(n)=\{1\ 3\ 7\ 10\ 10\ 7\ 2\}$ | Remember | 2 |
| 20. | Determine the convolution of the pairs of signals by means of z-transform $X_1(n)=(1/2)^n u(n)$ $X_2(n)=\cos\pi n u(n)$ | Remember | 2 |
| 22 | Find the inverse a-transform of $X(z)=\frac{z(z+1)}{(z-2)(z-1)^2}$ $\text{roc } z > 2$ using partial fraction method. | Remember | 2 |
| 23 | Determine the transfer function and impulse response of the system $y(n) - \frac{3}{4}y(n-1) + \frac{11}{88}y(n-2) = x(n) + \frac{11}{33}x(n-1)$. | Evaluate | 2 |
| 24 | Obtain the cascade and parallel form realizations for the following systems $Y(n) = -0.1(n-1) + 0.2 y(n-2) + 3x(n) + 3.6 x(n-1) + 0.6 x(n-2)$ | Apply | 2 |
| 25 | Obtain the Direct form II $y(n) = -0.1(n-1) + 0.72 y(n-2) + 0.7x(n) - 0.252 x(n-2)$ | Understand | 4 |
| 26 | Find the direct form- II realization of $H(z) = 8z-2+5z-1+1 / 7z-3+8z-2+1$ | Remember | 4 |
| 27 | Obtain the i) Direct forms ii) cascade iii) parallel form realizations for the following systems $y(n) = 3/4(n-1) - 1/8 y(n-2) + x(n) + 1/3 x(n-1)$ | Remember | 4 |
| 28 | Obtain the i) Direct forms ii) parallel form realizations for the following systems $y(n) = x(n) + 1/3 x(n-1) - 1/5 x(n-2)$ | Understand | 4 |

UNIT-I (ANALYTICAL THINKING QUESTIONS)

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| UNIT-I | | | |

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| INTRODUCTION | | | |
| 1 | Consider the simple signal processing system shown in below figure. The sampling periods of the A/D and D/A converters are $T=5\text{ms}$ and $T = 1\text{ms}$ respectively. Determine the output $y_a(t)$ of the system. If the input is $x_a(t)=3 \cos 100\pi t + 2 \sin 250\pi t$ (t in seconds) | Apply | 1 |
| 2 | Given the impulse response of a system as $h(k)=a^k u(k)$ determine the range of 'a' for which the system is stable | Remember | 2 |
| 3 | Determine the range of 'a' and 'b' for which the system is stable with impulse response $H(n)=\begin{cases} a^n & n \geq 0 \\ b^n & n < 0 \end{cases}$ | Apply | 1 |
| REALIZATION OF DIGITAL FILTERS | | | |
| 4 | Use the one-sided Z-transform to determine $y(n)$ $n \geq 0$ in the following cases. (a) $y(n) + y(n-1) - 0.25y(n-2) = 0$; $y(-1) = y(-2) = 1$ (b) $y(n) - 1.5y(n-1) + 0.5y(n-2) = 0$; $y(-1) = 1$; $y(-2) = 0$ | Apply | 2 |
| 5 | Prove that the fibonacci series can be thought of as the impulse response of the system described by the difference equation $y(n) = y(n-1) + y(n-2) + x(n)$ Then determine $h(n)$ using Z-transform techniques | Remember | 2 |
| | Obtain the i) Direct forms ii) cascade iii) parallel form realizations for the following systems $y(n) = 3/4 y(n-1) - 1/8 y(n-2) + x(n) + 1/3 x(n-1)$ | Apply | 4 |
| 6 | Find the direct form -I cascade and parallel form for $H(Z) = z^{-1} - 1 / 1 - 0.5 z^{-1} + 0.06 z^{-2}$ | Evaluate | 4 |

UNIT-II (SHORT ANSWER QUESTIONS)

| S.No | QUESTION | Blooms Taxonomy Level | Course Outcome |
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| UNIT-II DISCRETE FOURIER SERIES | | | |
| 1 | Define discrete fourier series? | Remember | 3 |
| 2 | Distinguish DFT and DTFT | Understand | 3 |
| 3 | Define N-point DFT of a sequence $x(n)$ | Remember | 3 |
| 4 | Define N-point IDFT of a sequence $x(n)$ | Remember | 3 |
| 5 | State and prove time shifting property of DFT. | Remember | 3 |
| 6 | Examine the relation between DFT & Z-transform. | Analyze | 3 |
| 7 | Outline the DFT $X(k)$ of a sequence $x(n)$ is imaginary | Understand | 3 |
| 8 | Outline the DFT $X(k)$ of a sequence $x(n)$ is real | Understand | 3 |
| 9 | Explain the zero padding ?What are its uses | Understand | 3 |
| 10 | Analyze about periodic convolution | Analyze | 3 |
| 11 | Define circular convolution. | Remember | 3 |
| 12 | Distinguish between linear and circular convolution of two sequences | Understand | 3 |
| 13 | Demonstrate the overlap-save method | Apply | 3 |
| 14 | Illustrate the sectioned convolution | Apply | 3 |
| 15 | Demonstrate the overlap-add method | Apply | 3 |
| 16 | State the difference between i)overlap-save ii)overlap-add method | Remember | 3 |

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| 17 | Compute the values of W_N^k , When $N=8$, $k=2$ and also for $k=3$. | Apply | 2 |
| 18 | Discuss about power density spectrum of the periodic signal | Understand | 3 |
| 19 | Compute the DTFT of the sequence $x(n)=a^n u(n)$ for $a<1$ | Apply | 2 |
| 20 | Show the circular convolution is obtained using concentric circle method? | Apply | 3 |
| FAST FOURIER TRANSFORM | | | |
| 21 | Why FFT is needed? | Remember | 6 |
| 22 | What is the speed improvement factor in calculation 64-point DFT of sequence using direct computation and FFT algorithm | Understand | 6 |
| 23 | What is the main advantages of FFT? | Understand | 6 |
| 24 | Determine $N=2048$, the number of multiplications required using DFT is | Evaluate | 6 |
| 25 | Determine $N=2048$, the number of multiplications required using FFT is | Evaluate | 6 |
| 26 | Determine, the number of additions required using DFT is | Evaluate | 6 |
| 27 | Determine $N=2048$, the number of additions required using FFT is | Evaluate | 6 |
| 28 | What is FFT | Remember | 6 |
| 29 | What is radix-2 FFT | Remember | 6 |
| 30 | What is decimation –in-time algorithm | Remember | 6 |
| 31 | What is decimation –in frequency algorithm | Remember | 6 |
| 32 | What are the differences and similarities between DIF and DIT algorithms | Remember | 6 |
| 33 | What is the basic operation of DIT algorithm | Remember | 6 |
| 34 | What is the basic operation of DIF algorithm | Remember | 6 |
| 35 | Draw the butterfly diagram of DIT algorithm | Remember | 6 |
| 36 | How can we calculate IDFT using FFT algorithm | Understand | 6 |
| 37 | Draw the 4-point radix-2 DIT-FFT butterfly structure for DFT | Remember | 6 |
| 38 | Draw the 4-point radix-2 DIF-FFT butterfly structure for DFT | Apply | 6 |
| 39 | What are the Applications of FFT algorithms | Remember | 6 |
| 40 | Draw the Radix-N FFT diagram for $N=6$ | Apply | 6 |

UNIT-II (LONG ANSWER QUESTIONS)

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| UNIT-II DISCRETE FOURIER SERIES | | | |
| 1 | State and prove the circular time shifting and frequency shifting properties of the DFT. | Apply | 3 |
| 2 | Prove the following properties. <div style="text-align: center;"> i. $W_N^n x(n) \longleftrightarrow X((K+1))_N R_N(K)$ ii. $x^*(n) \longleftrightarrow X^*((-K))_N R_N(K)$ </div> | Understand | 3 |
| 3 | If $x(n)$ denotes a finite length sequence of length N , show that $x((-n))_N = x((N-n))_N$. | Apply | 3 |
| 4 | Define DFT of a sequence. Compute the N - point DFT of the sequence. | Apply | 3 |

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| | $X(n) = \text{Cos}(2\pi rn/N), 0 \leq n \leq N - 1 \text{ and } 0 \leq r \leq N - 1$ | | |
| 5 | Determine the fourier series spectrum of signals i)x(n)=cos√2πn ii)cosπn/3 | Remember | 3 |
| 7 | Derive relation between fourier transform and z-transform | Remember | 3 |
| 8 | Let X(k) be a 14-point DFT of a length 14 real sequence x(n).The first 8 samples of X(k) are given by X(0)=12 X(1)=-1+j3 X(2)=3+j4 X(3)=1-j5 X(4)=-2+2j X(5)=6+j3 X(6)=-2-j3 X(7)=10.Determine the remaining samples | Understand | 3 |
| 9 | compute DFT of a sequence (-1) ⁿ for N=4 | Apply | 3 |
| 10 | Find 4-point DFT of the following sequences (a) x(n)={1 -1 0 0} (b) x(n)={1 1 -2 -2} (c) x(n)=2 ⁿ (d) x(n)=sin(nπ/2) | Remember | 3 |
| 11 | Determine the circular convolution of the two sequences x1(n)={1 2 3 4} x2(n)={1 1 1 1} and prove that it is equal to the linear convolution of the same | Apply | 3 |
| 12 | Find the output y(n) of a filter whose impulse response is h(n) = {1 1 1} and input signal x(n) = {3 -1 0 1 3 2 0 1 2 1}. Using Overlap add overlap save method | Understand | 3 |
| 13 | Find the output y(n) of a filter whose impulse response is h(n) = {1 1 1} and input signal x(n) = {3 -1 0 1 3 2 0 1 2 1}. Using Overlap add method | Apply | 3 |
| 14 | Determine the impulse response for the cascade of two LTI systems having impulse responses h1(n)=(1/2) ⁿ * u(n) h2(n)=(1/4) ⁿ *u(n) | Apply | 3 |
| 15 | Find the output sequence y(n)if h(n)={1 1 1 1} and x(n)={1 2 3 1} using circular convolution | Apply | 3 |
| 16 | Find the convolution sum of x(n)=1 n = -2 0 1 = 2 n= -1 = 0 elsewhere and h(n) = δ (n) - δ (n-1) + δ (n-2) - δ (n-3) | Analyze | 3 |
| | FAST FOURIER TRANSFORM | | |
| 17. | Explain the inverse FFT algorithm to compute inverse DFT of N=8 sequence. Draw the flow graph for the same. | Evaluate | 6 |
| 18. | Draw the butterfly line diagram for 8 - point FFT calculation and briefly explain. Use decimation in-time algorithm. | Analyze | 6 |
| 19. | Find the DFT of a sequence x(n)={1 2 3 4 4 3 2 1} using DIF algorithm. | Understand | 6 |
| 20. | Find the 8-point DFT of sequence x(n)={1 1 1 1 1 0 0 0} | Evaluate | 6 |
| 21 | Compute the eight-point DFT of the sequence $X(n) = \begin{cases} 1 & 0 \leq n \leq 7 \\ 0 & \text{otherwise} \end{cases}$ by using DIF algorithms | Evaluate | 6 |
| 22 | Evaluate the 8-point DFT for the following sequences using DIT-FFT algorithm. x1(n) = 1 for -3 ≤ n ≤ 3 and 0 otherwise. | Apply | 6 |
| 23 | Compute 4-point DFT of a sequence x(n)={0 1 2 3} using DIT DIF algorithms | Evaluate | 6 |
| 24 | Compute IDFT of sequence X(K)={7 -.707-j.707 -j 0.707-j0.707 1 0.707+j0.707 j -.707+j.707} | Analyze | 6 |
| 25 | Compute the eight-point DFT of the sequence x(n)={0.5 0.5 0.5 0.5 0 0 0 0} using Radix DIT algorithm | Apply | 6 |
| 26 | Compute the eight-point DFT of the sequence x(n)={0.5 0.5 0.5 0.5 0 0 0 0} using radix DIF algorithm | Apply | 6 |
| 27 | Compute the DFT of a sequence x(n)={1 -1 1 -1} using DIT algorithm | Understand | 6 |
| 28 | Given x(n)=2 ⁿ and N=8 find X(k) using DIT-FFT algorithm | Apply | 6 |
| 29 | Compute the DFT of the sequence $x(n) = \cos \frac{n\pi}{2}$ where N=4 using DIF FFT | Understand | 6 |

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| | algorithm. | | |
| 30 | Find the IDFT of sequence $X(k)=\{1+j, 2-2j, 0, 1+2j, 0, 1-j\}$ using DIF algorithm | Evaluate | 6 |
| 31 | Find the IDFT of sequence $X(k)=\{8, 1+j, 2-1-j, 0, 1, 0, 1+j, 1-j, 2\}$ | Evaluate | 6 |
| 32 | Draw the signal flow graph for 16-point DFT using a) DIT algorithm b) DIF algorithm | Evaluate | 6 |
| 33 | Find the IDFT of a sequence $x(n)=\{0, 1, 2, 3, 4, 5, 6, 7\}$ using DIT-FFT algorithm. | Understand | 6 |

UNIT-II (ANALYTICAL THINKING QUESTIONS)

| S. No | QUESTION | Blooms Taxonomy Level | Course Outcome |
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| UNIT-II | | | |
| DISCRETE FOURIER SERIES | | | |
| 1 | The linear convolution of length-50 sequence with a length 800 sequence is to be computed using 64 point DFT and IDFT a) What is the smallest number of DFT and IDFT needed to compute the linear convolution using overlap-add method b) What is the smallest number of DFT and IDFT needed to compute the linear convolution using overlap-save method | Apply | 3 |
| 2 | Consider the sequences $x_1(n) = \{0, 1, 2, 3, 4\}$, $x_2(n) = \{0, 1, 0, 0, 0\}$, $x_3(n) = \{1, 0, 0, 0, 0\}$ and their 5 point DFT. (a) Determine a sequence $y(n)$ so that $Y(k) = X_1(k) X_2(k)$ (b) Is there a sequence $x_3(n)$ such that $S(k) = X_1(k) X_3(k)$ | Analyze | 3 |
| FAST FOURIER TRANSFORM | | | |
| 3 | Find the IDFT of sequence $X(k)=\{4, 1-j, 2.414, 0, 1-j, 4.14, 0, 1+j, 4.14, 0, 1+j, 2.414\}$ using DIF algorithm | Remember | 6 |
| 4 | Explain how the DFT can be used to compute N equi-spaced samples of the z-transform of an N-point sequence on a circle of radius r. | Remember | 6 |
| 5 | Evaluate and compare the 8-point for the following sequences using DIT-FFT algorithm. a) $x_1(n) = \begin{cases} 1 & \text{for } -3 \leq n \leq 3 \\ 0 & \text{otherwise} \end{cases}$ b) $x_2(n) = \begin{cases} 1 & \text{for } 0 \leq n \leq 6 \\ 0 & \text{otherwise} \end{cases}$ | Apply | 6 |

UNIT-III (SHORT ANSWER QUESTIONS)

| S.No | QUESTION | Blooms Taxonomy Level | Course Outcome |
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| UNIT-III | | | |
| IIR DIGITAL FILTERS | | | |
| 1 | Give the magnitude function of butter worth filter. What is the effect of varying order of N on magnitude and phase response? | Understand | 5 |
| 2 | Give any two properties of butter worth low pass filter | Remember | 5 |
| 3 | What are properties of chebyshev filter | Remember | 5 |
| 4 | Give the equation for the order of N and cutoff frequency of butter worth filter | Remember | 5 |
| 5 | What is an IIR filter? | Remember | 5 |
| 6 | What is meant by frequency warping? What is the cause of this effect? | Remember | 5 |

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| 7 | Distinguish between butterworth and chebyshev filter | Understand | 5 |
| 8 | How can design digital filters from analog filters | Evaluate | 5 |
| 9 | What is bilinear transformation and properties of bilinear transform | Remember | 5 |
| 10 | What is impulse invariant method of designing IIR filter | Remember | 5 |
| 11 | Distinguish IIR and FIR filters | Analyze | 5 |
| 12 | Distinguish analog and digital filters | Analyze | 5 |
| 13 | Give the equation for the order N, major, minor axis of an ellipse in case of chebyshev filter? | Understand | 5 |
| 14 | List the Butterworth polynomial for various orders | Remember | 5 |
| 15 | Write the various frequency transformations in analog domain? | Evaluate | 5 |
| 16 | What are the advantages of Chebyshev filters over Butterworth filters | Understand | 5 |
| 17 | What do you understand by backward difference | Understand | 5 |
| 18 | Write a note on pre warping. | Evaluate | 5 |
| 19 | What are the specifications of a practical digital filter | Evaluate | 5 |
| 20 | Write the expression for the order of chebyshev filter and Butterworth filter | Analyze | 5 |

UNIT-III (LONG ANSWER QUESTIONS)

| S. No | QUESTION | Blooms Taxonomy Level | Course Outcome |
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| UNIT-III | | | |
| IIR DIGITAL FILTERS | | | |
| 1 | Design a Digital IIR low pass filter with pass band edge at 1000 Hz and stop band edge at 1500 Hz for a sampling frequency of 5000 Hz. The filter is to have a pass band ripple of 0.5 dB and stop band ripple below 30 dB. Design Butter worth filler using impulse invariant transformation . | Evaluate | 5 |
| 2 | Design a Digital IIR low pass filter with pass band edge at 1000 Hz and stop band edge at 1500 Hz for a sampling frequency of 5000 Hz. The filter is to have a pass band ripple of 0.5 dB and stop band ripple below 30 dB. Design Butter worth filler using Bi-linear transformation . | Understand | 5 |
| 3 | Given the specification $\alpha_p=1\text{dB}$, $\alpha_s=30\text{dB}$, $\Omega_p=200\text{rad/sec}$, $\Omega_s=600\text{rad/sec}$. Determine the order of the filter | Understand | 5 |
| 4 | Determine the order and the poles of lowpass butter worth filter that has a 3 dB attenuation at 500Hz and an attenuation of 40dB at 1000Hz | Remember | 5 |
| 5 | Design an analog Butterworth filter that as a -2dB pass band attenuation at a frequency of 20rad/sec and at least -10dB stop band attenuation at 30rad/sec | Understand | 5 |
| 6 | For the given specification design an analog Butterworth filter $0.9 \leq H(j\Omega) \leq 1$ for $0 \leq \Omega \leq 0.2\pi$ $ H(j\Omega) \leq 0.2$ for $0.4\pi \leq \Omega \leq \pi$ | Remember | 5 |
| 7 | For the given specifications find the order of butter worth filter $\alpha_p=3\text{dB}$, $\alpha_s=18\text{dB}$, $f_p=1\text{KHz}$, $f_s=2\text{KHz}$. | Evaluate | 5 |
| 8 | Design an analog butter worth filter that has $\alpha_p=0.5\text{dB}$, $\alpha_s=22\text{dB}$, $f_p=10\text{KHz}$, $f_s=25\text{KHz}$ Find the pole location of a 6 th order butter worth filter with $\Omega_c=1$ rad/sec | Understand | 5 |
| 9 | Given the specification $\alpha_p=3\text{dB}$, $\alpha_s=16\text{dB}$, $f_p=1\text{KHz}$, $f_s=2\text{KHz}$. Determine the order of the | Understand | 5 |

| S. No | QUESTION | Blooms Taxonomy Level | Course Outcome |
|-------|--|-----------------------|----------------|
| | filter Using cheby shev approximation. find H(s). | | |
| 10 | Obtain an analog cheby shev filter transfer function that satisfies the constraints $0 \leq H(j\Omega) \leq 1$ for $0 \leq \Omega \leq 2$ | Evaluate | 5 |
| 11 | Determine the order and the poles of type 1 low pass cheby shev filter that has a 1 dB ripple in the passband and passband frequency $\Omega_p = 1000\pi$ and a stopband of frequency of 2000π and an attenuation of 40dB or more. | Evaluate | 5 |
| 12 | For the given specifications find the order of chebyshev-I $\alpha_p = 1.5\text{dB}$, $\alpha_s = 10\text{dB}$, $\Omega_p = 2\text{rad/sec}$, $\Omega_s = 30\text{ rad/sec}$. | Analyze | 5 |
| 13 | For the analog transfer function $H(s) = \frac{2}{(s+1)(s+2)}$ Determine H(z) using impulse invariance method .Assume T=1sec | Understand | 5 |
| 14 | For the analog transfer function $H(s) = \frac{1}{s^2 + \sqrt{2}s + 1}$ Determine H(z) using impulse invariance method .Assume T=1sec | Remember | 5 |
| 15 | Design a third order butter worth digital filter using impulse invariant technique .Assume sampling period T=1sec | Understand | 5 |
| 16 | An analog filter has a transfer function $H(s) = \frac{5}{s^3 + 6s^2 + 11s + 6}$.Design a digital filter equivalent to this using impulse invariant method for T=1Sec | Remember | 5 |
| 17 | For the analog transfer function $H(s) = \frac{2}{(s+1)(s+2)}$ Determine H(z) using bilinear method Assume T=1sec | Evaluate | 5 |

UNIT-III (ANALYTICAL THINKING QUESTIONS)

| S. No | QUESTION | Blooms Taxonomy Level | Course Outcome |
|----------------------------|--|-----------------------|----------------|
| UNIT-III | | | |
| IIR DIGITAL FILTERS | | | |
| 1 | For the analog transfer function $H(s) = \frac{1}{s^2 + 6s + 9}$ Determine H(z) using bilinear method | Understand | 5 |
| 2 | Apply impulse invariant method and find H(z) for $H(s) = \frac{s+a}{(s+a)^2 + b^2}$ | Remember | 5 |
| 3 | Design a chebyshev filter with a maximum pass band attenuation of 2.5dB at $\Omega_p = 20\text{rad/sec}$ and the stopband attenuation of 30dB at $\Omega_s = 50\text{rad/sec}$. | Remember | 5 |
| 4 | An ideal discrete-time lowpass filter with cutoff frequency $\omega_c = 2\pi/5$ was designed using impulse invariance from an ideal continuous-time lowpass filter with cutoff frequency $\Omega_c = 2\pi(4000)\text{ rad/s}$. What was the value of T? is this value unique? If not, find another value of T consistent with the | Evaluate | 5 |

| S. No | QUESTION | Blooms Taxonomy Level | Course Outcome |
|-------|--|-----------------------|----------------|
| | information given. | | |
| 5 | The bilinear transformation is used to design an ideal discrete-time lowpass filter with cutoff frequency $\omega_c = 3\pi/5$ from an ideal continuous-time lowpass filter with cutoff frequency $\Omega_c = 2\pi(300)$ rad/s. What was the value of T? Is this value unique? If not, find another value of T consistent with the information given. | Understand | 5 |

UNIT-IV (SHORT ANSWER QUESTIONS)

| S.No | QUESTION | Blooms Taxonomy Level | Course Outcome |
|----------------------------|--|-----------------------|----------------|
| UNIT-IV | | | |
| FIR DIGITAL FILTERS | | | |
| 1 | What is meant by FIR filter? and What are advantages of FIR filter? | Understand | 8 |
| 2 | What is the necessary and sufficient condition for the linear phase characteristic of a FIR filter? | Remember | 8 |
| 3 | List the well known design technique for linear phase FIR filter design? | Understand | 8 |
| 4 | For What kind of Apply, the symmetrical impulse response can be used? | Remember | 8 |
| 5 | Under What conditions a finite duration sequence h(n) will yield constant group delay in its frequency response characteristics and not the phase delay? | Evaluate | 8 |
| 6 | What is Gibbs phenomenon? | Understand | 8 |
| 7 | What are the desirable characteristics of the windows? | Understand | 8 |
| 8 | Compare Hamming window with Kaiser window. | Evaluate | 8 |
| 9 | Draw impulse response of an ideal lowpass filter. | Evaluate | 8 |
| 10 | What is the principle of designing FIR filter using frequency sampling method? | Analyze | 8 |
| 11 | For What type of filters frequency sampling method is suitable? | Understand | 8 |
| 12 | What is the effect of truncating an infinite Fourier series into a finite series? | Remember | 8 |
| 13 | What is a Kaiser window? In What way is it superior to other window functions? | Understand | 8 |
| 14 | Explain the procedure for designing FIR filters using windows. | Remember | 8 |
| 15 | What are the disadvantages of Fourier series method? | Evaluate | 8 |
| 16 | Draw the frequency response of N point Bartlett window | Understand | 8 |
| 17 | Draw the frequency response of N point Blackman window | Understand | 8 |
| 18 | Draw the frequency response of N point Hanning window | Evaluate | 8 |
| 19 | What is the necessary and sufficient condition for linear phase characteristics in FIR filter. | Evaluate | 8 |
| 20 | Give the equation specifying Kaiser window. | Analyze | 8 |

UNIT-IV (LONG ANSWER QUESTIONS)

| S. No | QUESTION | Blooms Taxonomy Level | Course Outcome |
|----------------------------|---|-----------------------|----------------|
| UNIT-IV | | | |
| FIR DIGITAL FILTERS | | | |
| 1 | Design a high pass filter using hamming window with a cut-off frequency of 1.2 radians/second and N=9 | Evaluate | 8 |
| 2 | Determine the frequency response of FIR filter defined by $y(n)=0.25x(n)+x(n-1)+.25x(n-2)$ Calculate the phase delay and group delay. | Understand | 8 |
| 3 | The frequency response of Linear phase FIR filter is given by | Remember | 8 |

| S. No | QUESTION | Blooms Taxonomy Level | Course Outcome |
|-------|--|-----------------------|----------------|
| | $H(e^{j\omega}) = \cos \frac{\omega}{2} + \frac{1}{2} \cos \frac{3\omega}{2}$. Determine the impulse response(n). | | |
| 4 | Design an ideal highpass filter with a frequency response $H_d(e^{j\omega}) = 1$ for $\frac{\pi}{4} \leq \omega \leq \pi$ and 0 for $ \omega \leq \frac{\pi}{4}$ Find the values of h(n) for N=11. Find H(z). plot magnitude response. | Remember | 8 |
| 5 | Design an ideal bandpass filter with a frequency response $H_d(e^{j\omega}) = 1$ for $\frac{\pi}{4} \leq \omega \leq \frac{3\pi}{4}$ and 0 for $ \omega \leq \frac{\pi}{4}$ or $ \omega \geq \frac{3\pi}{4}$ Find the values of h(n) for N=11. Find H(z). plot magnitude response. | Evaluate | 8 |
| 6 | Design an ideal band reject filter with a frequency response $H_d(e^{j\omega}) = 1$ for $ \omega \leq \frac{\pi}{3}$ and $ \omega \geq \frac{2\pi}{3}$ and 0 for otherwise Find the values of h(n) for N=11. Find H(z). plot magnitude response. | Understand | 8 |
| 7 | Design an ideal differentiator $H(e^{j\omega}) = j\omega$ for $-\pi \leq \omega \leq \pi$ Using a) rectangular window b) Hamming window with N=8. plot frequency response in both cases. | Understand | 8 |
| 8 | Using frequency sampling method design a bandpass filter with following specifications Sampling frequency F=8000Hz Cut off frequency $f_{c1}=1000\text{Hz}$ $f_{c2}=3000\text{Hz}$ Determine the filter coefficients for N=7 | Evaluate | 8 |
| 9 | Compare IIR and FIR filters | Analyze | 8 |
| 10 | Using a rectangular window technique design a low pass filter with pass band gain of unity, cutoff frequency of 100Hz and working at a sampling frequency of 5KHz. The length of the impulse response should be 7. | Remember | 8 |
| 11 | Design a HPF of length 7 with cut off frequency of 2 rad/sec using Hamming window. Plot the magnitude and phase response. | Remember | 8 |
| 12 | Explain the principle and procedure for designing FIR filter using rectangular window | Evaluate | 8 |

UNIT-IV (ANALYTICAL THINKING QUESTIONS)

| S. No | QUESTION | Blooms Taxonomy Level | Course Outcome |
|--|---|-----------------------|----------------|
| UNIT-IV FIR DIGITAL FILTERS | | | |
| 1 | Design a filter with $H_d(e^{j\omega}) = e^{-j\omega}$, $\pi/4 \leq \omega \leq \pi/4$ 0 for $\pi/4 \leq \omega \leq \pi$ using a Hamming window with N=7. | Understand | 8 |
| 2 | $H(\omega) = 1$ for $ \omega \leq \pi/3$ and $ \omega \geq 2\pi/3$ otherwise for N=11. and find the response | Remember | 8 |
| 3 | a) Prove that an FIR filter has linear phase if the unit sample response satisfies the condition $h(n) = \pm h(M-1-n)$, $n=0,1,\dots, M$. Also discuss symmetric and anti symmetric cases of FIR filter. b) Explain the need for the use of window sequence in the design of FIR filter. | Understand | 8 |

| S. No | QUESTION | Blooms Taxonomy Level | Course Outcome |
|-------|--|-----------------------|----------------|
| | Describe the window sequence generally used and compare the properties. | | |
| 4 | Design an ideal differentiator with frequency response $H(e^{j\omega}) = j\omega$ $-\pi \leq \omega \leq \pi$ using hamming window for $N=8$ and find the frequency response. | Remember | 8 |
| 5 | Design an ideal Hilbert transformer having frequency response $H(e^{j\omega}) = j$ $-\pi \leq \omega \leq 0$ $-j$ $0 \leq \omega \leq \pi$ for $N=11$ using rectangular window | Evaluate | 8 |

UNIT-V (SHORT ANSWER QUESTIONS)

| S.No | QUESTION | Blooms Taxonomy Level | Course Outcome |
|--|---|-----------------------|----------------|
| UNIT-V | | | |
| MULTIRATE DIGITAL SIGNAL PROCESSING | | | |
| 1 | What is decimation by factor D | Understand | 7 |
| 2 | What is interpolation by factor I | Remember | 7 |
| 3 | Find the spectrum of exponential signal | Understand | 7 |
| 4 | Find the spectrum of exponential signal decimated by factor 2. | Remember | 7 |
| 5 | Find the spectrum of exponential signal interpolated by factor 2 | Evaluate | 7 |
| 6 | Explain the term up sampling and down sampling | Understand | 7 |
| 7 | What are the Applys of multi rate DSP | Understand | 7 |
| 8 | What does multirate mean? | Evaluate | 7 |
| 9 | Why should I do multirate DSP? | Evaluate | 7 |
| 10 | What are the categories of multirate? | Analyze | 7 |
| 11 | What are "decimation" and "downsampling"? | Understand | 7 |
| 12 | What is the "decimation factor"? | Remember | 7 |
| 13 | Why decimate? | Understand | 7 |
| 14 | Is there a restriction on decimation factors I can use? | Remember | 7 |
| 15 | Which signals can be down sampled? | Evaluate | 7 |
| 16 | What happens if I violate the Nyquist criteria in down sampling or decimating? | Understand | 7 |
| 17 | Can I decimate in multiple stages? | Understand | 7 |
| 18 | How do I implement decimation | Evaluate | 7 |
| FINITE WORDLENGTH EFFECTS | | | |
| 19 | What are the effects of finite word length in digital filters? | Remember | 7 |
| 20 | List the errors which arise due to quantization process. | Understand | 4 |
| 21 | Discuss the truncation error in quantization process. | Understand | 4 |
| 22 | Write expression for variance of round-off quantization noise. | Evaluate | 4 |
| 23 | Define limit cycle Oscillations, and list out the types. | Evaluate | 4 |
| 24 | When zero limit cycle oscillation and Over flow limit cycle oscillation has occur? | Evaluate | 4 |
| 25 | Why? Scaling is important in Finite word length effect. | Understand | 7 |
| 26 | What are the differences between Fixed and Binary floating point number representation? | Evaluate | 7 |
| 27 | What is the error range for Truncation and round-off process? | Evaluate | 4 |
| 28 | What do you understand by a fixed-point number? | Analyze | 7 |
| 29 | What is meant by block floating point representation? What are its advantages? | Remember | 7 |
| 30 | What are the advantages of floating point arithmetic? | Understand | 7 |
| 31 | How the multiplication & addition are carried out in floating point arithmetic? | Understand | 7 |

| S.No | QUESTION | Blooms Taxonomy Level | Course Outcome |
|------|--|-----------------------|----------------|
| 32 | What do you understand by input quantization error? | Evaluate | 4 |
| 33 | What is the relationship between truncation error e and the bits b for representing a decimal into binary? | Evaluate | 4 |
| 34 | What is meant rounding? Discuss its effect on all types of number representation? | Evaluate | 4 |
| 35 | What is meant by A/D conversion noise? | Understand | 4 |
| 36 | What is the effect of quantization on pole location? | Evaluate | 4 |
| 37 | What is meant by quantization step size? | Evaluate | 4 |
| 38 | How would you relate the steady-state noise power due to quantization and the b bits representing the binary sequence? | Analyze | 4 |

UNIT-V (LONG ANSWER QUESTIONS)

| S. No | QUESTION | Blooms Taxonomy Level | Course Outcome |
|--|--|-----------------------|----------------|
| UNIT-V | | | |
| MULTIRATE DIGITAL SIGNAL PROCESSING | | | |
| 1 | Discuss the applications of Multirate Digital Signal Processing | | |
| 2 | Consider a signal $x(n) = u(n)$ <ol style="list-style-type: none"> i. Obtain a signal with a decimation factor '3' ii. Obtain a signal with a interpolation factor '3'. | | |
| 3 | Derive the expression for decimation by factor D | Understand | 7 |
| 4 | Derive the expression for interpolation by factor I | Analyze | 7 |
| 5 | With the help of block diagram explain the sampling rate conversion by a rational factor ' I/D '. Obtain necessary expressions. | Evaluate | 7 |
| 6 | Write notes on filter design and implementation for sampling rate conversion | Analyze | 7 |
| FINITE WORDLENGTH EFFECTS | | | |
| 7 | Explain the output noise due to A/D conversion of the input $x(n)$. | Evaluate | 7 |
| 8 | Write short note on (a) Truncation and rounding (b) Coefficient Quantization. | Evaluate | 4 |
| 9 | Explain the errors introduced by quantization with necessary expression | Understand | 4 |
| 10 | (i). Discuss the various common methods of quantization. (ii). Explain the finite word length effects in FIR digital filters. | Apply | 4 |
| 11 | Describe the quantization in floating point realization of IIR digital filters. (i). Explain the characteristics of limit cycle oscillation with respect to the system described by the difference equation: $y(n) = 0.95y(n-1) + x(n)$; $x(n) = 0$ and $y(-1) = 13$. Determine the dead band range of the system. (ii). Explain the effects of coefficient quantization in FIR filters | Understand | 4 |
| 12 | (i). Derive the signal to quantization noise ratio of A/D converter. (ii). Compare the truncation and rounding errors using fixed point and floating point representation. | Analyze | 4 |
| 13 | (i). What is quantization of analog signals? Derive the expression for the quantization error. (ii). Explain coefficient quantization in IIR filter. | Evaluate | 7 |

| S. No | QUESTION | Blooms Taxonomy Level | Course Outcome |
|-------|---|-----------------------|----------------|
| 14 | (i). How to prevent limit cycle oscillations? Explain. (ii). What is meant by signal scaling? Explain. | Analyze | 7 |
| 15 | Discuss in detail the errors resulting from rounding and truncation. | Evaluate | 4 |
| 16 | Explain the limit cycle oscillations due to product round off and overflow errors. | Analyze | 7 |
| 17. | Explain the characteristics of a limit cycle oscillation with respect to the system described by the equation $y(n) = 0.45y(n - 1) + x(n)$ when the product is quantized to 5 – bits by rounding. The system is excited by an input $x(n) = 0.75$ for $n = 0$ and $x(n) = 0$ for $n \neq 0$. Also determine the dead band of the filter. | Evaluate | 7 |
| 18. | Consider the LTI system governed by the equation, $y(n) + 0.8301y(n - 1) + 0.7348y(n - 2) = x(n - 2)$. Discuss the effect of co-efficient quantization on pole location , when the coefficients are quantized by 3-bits by truncation 4-bits by truncation | Evaluate | 7 |

UNIT-V (ANALYTICAL THINKING QUESTIONS)

| S. No | QUESTION | Blooms Taxonomy Level | Course Outcome |
|--|---|-----------------------|----------------|
| UNIT-V | | | |
| MULTIRATE DIGITAL SIGNAL PROCESSING | | | |
| 1 | a)Describe the decimation process with a neat block diagram. b)Consider a signal $x(n)=\sin(\frac{\pi}{4}n)U(n)$. Obtain a signal with an interpolation factor of '2' | Understand | 7 |
| 2 | a) What are the advantages and drawbacks of multirate digital signal processing b) Design a decimator with the following specification $D = 5$, $\delta_p = 0.025$ $\delta_s = 0.0035$, $\omega_s = 0.2\pi$ Assume any other required data. | Evaluate | 7 |
| FINITE WORDLENGTH EFFECTS | | | |
| 3 | The output of an A/D is fed through a digital system whose system function is $H(z)=1/(1-0.8z^{-1})$.Find the output noise power of the digital system. | Evaluate | 7 |
| 4 | The output of an A/D is fed through a digital system whose system function is $H(Z)=0.6z/z-0.6$. Find the output noise power of the digital system=8 bits | Evaluate | 4 |
| 5 | Discuss in detail about quantization effect in ADC of signals. Derive the expression for $P_e(n)$ and SNR. | Understand | 4 |
| | A digital system is characterized by the difference equation $y(n)=0.95y(n-1)+x(n)$.determine the dead band of the system when $x(n)=0$ and $y(-1)=13$. | Understand | 4 |
| 6 | Two first order filters are connected in cascaded whose system functions of the individual sections are $H1(z)=1/(1-0.8z^{-1})$ and $H2(z)=1/(1-0.9z^{-1})$). Determine the overall output noise power. | Evaluate | 4 |